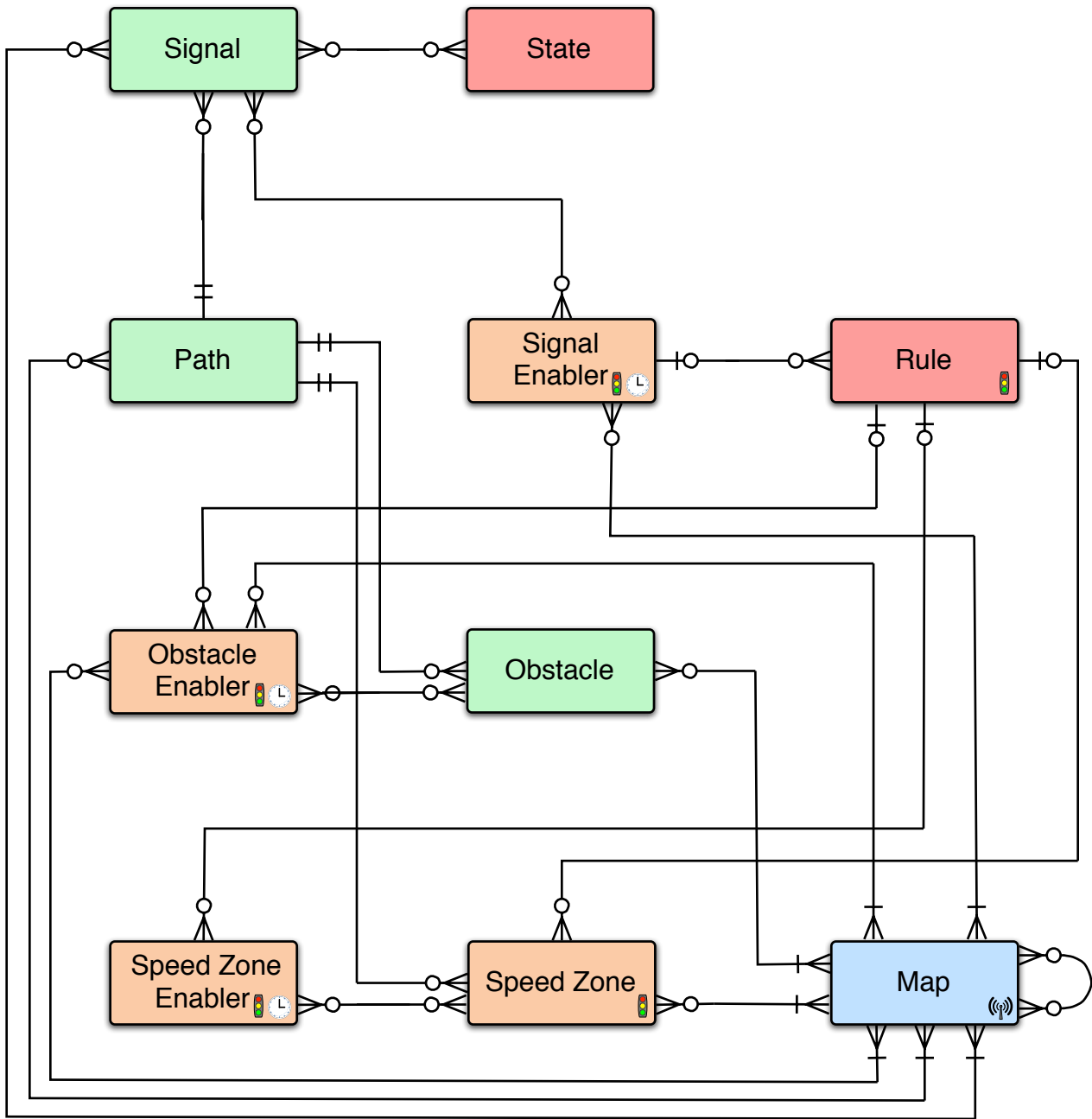


# OSID MAPPING PATH RULES MODEL



**Signal**  
Coordinate getCoordinate()

**Obstacle**  
Coordinate getStartingCoordinate()  
Coordinate getEndingCoordinate()

**SpeedZone**  
Coordinate getStartingCoordinate()  
Coordinate getEndingCoordinate()  
boolean isImplicit()  
Speed getSpeedLimit()

## LEGEND

